IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

In re Patent Application of

GATE

Serial No. 07/052,111

Filed: April 24, 1987

Atty. Ref.: SCS-540-388

TC/A.U.: 3643

Examiner: T. Collins

For: MISSILES AND CONTROL SYSTEMS THEREFOR

November 28, 2007

Commissioner for Patents P.O. Box 1450

Alexandria, VA 22313-1450

Sir:

SUBMISSION OF PRIORITY DOCUMENTS

It is respectfully requested that this application be given the benefit of the foreign filing date under the provisions of 35 U.S.C. §119 of the following, a certified copy of which is submitted herewith:

Application No.

Country of Origin

Filed

8129316

UK

29 September 1981

Respectfully submitted,

NIXON & VANDERHYE P.

By:

Stanley & Spooner Reg. No. 27.393

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THE PATENT OFFICE,
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I further certify that pursuant to Section 22(1) of the Patents ct, 1977, the Comptroller has ordered prohibition of publication of he said specification.



WITNESS my hand this 22 day of CCTOBER

1982

C.O.C. 6 (s.s.)

Bowkennard

PATENTS ACT 1977

ATENTS FORM NO. 1/77 lules 6, 16, 19) HANDLE AS U.S.

The Comptroller
The Patent Office
25 Southampton Buildings

EFFECTIVE FORM

For fee stamp See original Form

	Applicant's or Agent's Reference (Please insert if available) 20-1966D (NA/102)				
H	Title of Invention IMPROVE	MENTS IN OR RE	LATING TO GUIDANCE SYST	EM	
111	Applicant or Applicants (See note 2)				
	Name (First or only applicant) British Aerospace Public Limited Company.				
	Address				
	London, SW1Y 5HR.				
	Nationalitya British Company.				
	Name (of second applicant, if more than one)				
			<u>, , , , , , , , , , , , , , , , , , , </u>		
V	Inventor (See note 3) SEX XXXX MODICENCES & SERVING SORE BOOD NOW MOTE or (b) A statement on Patents Form No. 7/77% will be furnished				
	Authorisation of Agent (See note 4) D. J. SAUL - GENERAL AUTHORISATION.				
,	Additionation of Again (388 note 4				
/	Address for Service (See note 5) (Tel: Weybridge 45522, Ext. 541).	British Aerospa Corporate Pater Brooklands Road	ace Public Limited Comp nts Department, (Bldg. d, rrey, KT13 OSJ.	any T3	
/ /1	Address for Service (See note 5) (Tel: Weybridge 45522, Ext. 541).	British Aerospa Corporate Pater Brooklands Road Weybridge, Su	nts Department, (Bldg.	T3	
	Address for Service (See note 5) (Tel: Weybridge 45522, Ext. 541) Declaration of Priority (See note 6) Country	British Aerospa Corporate Pater Brooklands Road Weybridge, Sur Filing date	nts Department, (Bldg. d, rrey, KT13 OSJ.	т3	
	Address for Service (See note 5) (Tel: Weybridge 45522, Ext. 541). Declaration of Priority (See note 6) Country	British Aerospa Corporate Pater Brooklands Roac Weybridge, Sun Filing date	nts Department, (Bldg. d, rrey, KTl3 OSJ.	тз 	

Â.	The application contains the following number of sheet(s)	B The application as filed is accompanied by:
1	Requast	1 Priority document
2	Description6 Sheat(s)	2 Translation of priority document
3	Claim(s)Sheet(s)	3 Request for Search
4	Drawing(s)Sheet(s)	4 Statement of Inventorship and Right to Grant
5	Abstract Sheet(s)	5 Separate Authorisation of

ΧI Signature (See note 8)

D. J. SAUL - CHARTERED PATENT AGENT

NOTES:

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'IMPROVEMENTS IN OR RELATING TO GUIDANCE SYSTEMS'

29 SEP 198

NOT TO BE AMENDED.

8129316

This invention relates to guidance systems and in particular to guidance systems with restricted fields of view.

Restriction of the fields of view of guidance systems sensors can give considerable advantages, for example in a guided missile when the target sensor is mounted in a position remote from the nose of the missile. Our co-pending Application No. 80 10353 refers to such an arrangement.

However, existing missile control systems are not able to maintain the target sight line sufficient for navigation, while the missile flies an intercept course if the sensor field of view is greatly restricted.

It is an aim of the present invention to provide means for the navigation of a missile to target interception, in a missile having a restricted field of view. Some loss of sight line may be tolerable.

According to the present invention there is provided means for translation of sensor commands into roll commands, said roll commands limited to ensure that the sight line is mtaintained sufficiently and additional steering commands conditioned by said roll commands.

The invention may be used when the responses to the navigation demands for desired lateral acceleration values (L_{H} and L_{J}) are approximately linear in axes not spinning about the missile but corresponding to it.

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By way of example one embodiment of the invention will now be described with reference to the accompanying figures in which

Fig.1 illustrates typical fields of view;

Fig.2 shows a block diagram of embodiment of the invention;

Fig. 3 shows a possible implementation of two lateral autopilots used to improve roll rate capability.

With reference to Fig.1 LJn and LHn are the demands for LJ and LH (Fig.2) derived for a standard navigation law for example Acceleration Vectored Navigation (described in Guided Eapon Control Systems by P. Garnell and D.J. East (Pergamon Press 1977) Section 9.9. The invention modifies these demands to provide demands that match LJn and LHn subject to the constraints imposed by the limited field of view.

Block 1 converts the cartesian components LJn and LHn to polar coordinate form and gives outputs proportional to angle

$$= \left\{ \begin{array}{ll} (\text{arg (LJn, LHn)} & -\pi < \emptyset < \pi \\ \text{o} & \text{otherwise} \end{array} \right\}$$

and amplitude λ

$$\lambda = \sqrt{(LJn^2 + LHn^2)}$$

Block 2 gives an absolute value and 3 is a threshold detector. If the threshold value of 3 is exceeded logic switch 4 switches from the current value to the previous computed value through 5. This arrangement reduces any tendency towards violent manoeuvres that may be caused by noise or small perturbations. A limiter 6 has limits controlled by the logical switch 7

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which switches from multiplied by gain K at 9 for a false (zero) input to max for a true input. The output from the limiter 6 is multiplied by a gain $_{\rm p}$ 8 to give the demand Pd to a roll rate or roll control system. Filtering of Pd using standard techniques may be required.

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The λ output from 1 is also an input to threshold detector 10 from which a 0 or 1 logic output goes to the OR gate 12. The other input to 12 is derived from threshold detector 11. The input to 11 from 13 is an indication of the target sight line separation from the missile axis for example $\sqrt{LH^2 + LJ^2}$ and is calculated by 13. The output from 12 is used to operate the logic switches 14 and 15 as well as 7. The operation of the lower limiter 16 of LJn is set by the output of 15. The upper limiter of LJn is 17 and the output from 17 is the demand in one axis.

A computation at 18 using the outputs ϕd from 6 and LJd from 17 gives LHd

where

L'Hd = LJd tan ød

The error between L'Hd and LHn is the input to the limiter 19 controlled by switch 14. The output from 19 is added to LHn and is the demand for the other axis LHd.

The \$\phi\$ output from 1 gives a measure of the angle between the raw demanded look angle direction and the current direction of the field of view slit. This is used after some modification to provide an error signal to drive the missile roll demands. Using the raw look angle demands instead of the measured look angle to drive the rolling motion of the missile has the advantage of providing the missile with advanced warning of the intended rolling motion so the missile tends to roll in the right direction long before the measured look angle makes this necessary. In the presence of noise and roll limiting by 6 the demands Pd can change sign rapidly causing time to be lost before the missile is demanded to roll in the correct direction for instance if the demands are near \$\pm\$ not to be lost before the missile is demanded to roll in the correct direction for instance if the demands are near \$\pm\$ not not not consider the demands are near \$\pm\$ not consider the not consider the demands are near \$\pm\$ not consider the not consider the not consider the near \$\pm\$ not consider the not consider the near \$\pm\$ not consider the near \$\p



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are near t π . the limiter 6 is included so that the missile does not roll fast enough to cause an out of plane or underdemped response from a standard autopilot that is responding to LHd and LJd.

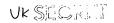
The arrangement of 1, 10, 11, 13 and 12 is used to indicate when the demands and look angle are small enough to make the missile fly momentarily within the restricted field of view A of figure 1. The output from 12 Bd is false (zero) in this case.

When Bd equals zero the rolling of the missile has little consistent effect on the pitching of the missile and the limited lateral look angle capability of the missile is used to reduced the roll control demands in proportion to λ as indicated by 9 and 7. A similar effect could be achieved by changing the value of the gain Kp 8 instead of the limit. 18 is used to give a demand for LH that matches the roll demand ϕd and thus keeps the target near the LJ axis in figure 2.

Normally the limits in 19 are set to zero when Bd = 1 and opened up when Bd = 0 so that the lateral look angle capability of the missile can be used in this case. Similarly for the control of the limits of 16 by 15. The limit 17 is not essential but may be included to slightly extend the missile tracking capability in cases when the field of view is needed.

Preferably the invention would be implemented using microprocessors and take the form of a small computer. One example of an autopilot suitable for use with this invention is given in Garnell and East section 6.10. for roll control.

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Two identical autopilots may be used one for pitch and one for yaw for example Garnell and East section 6.3.

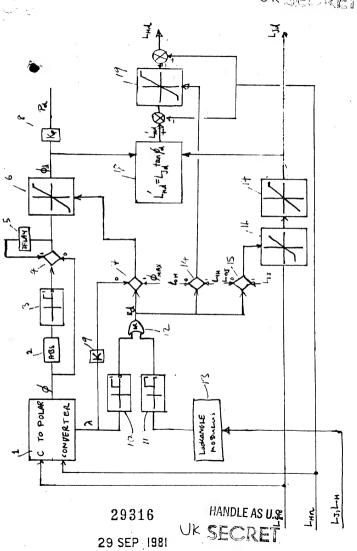
The roll rate capability of the missile may be improved by advancing the demands in the direction of rotation as a function of roll rate to compensate for the lag produced by the actuator. Fig 3 shows a possible implementation,

Those skilled in the art will recognise that the priorities of roll signals and conditioned steering signals may be varied to advantage for other applications.

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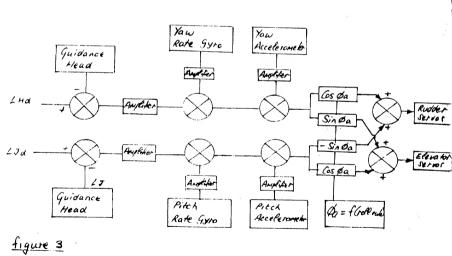




Restricted Freder J wews A

Figure 2

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